

# Classical and Quantum Nonlinear Dynamics

## Frühjahrssemester 2024

### Blatt 4

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(1) **Conservative systems** (2 Punkte)

Given a system  $\dot{\mathbf{x}} = \mathbf{f}(\mathbf{x})$ , a *conserved quantity* is a real-valued continuous function  $E(\mathbf{x})$  that is constant on trajectories, i.e.,  $dE/dt = 0$ .

To avoid trivial examples, we also require that  $E(\mathbf{x})$  be nonconstant on every open set. Show that a conservative system (i.e., a system for which a conserved quantity exists) cannot have any attractive fixed points.

(2) **Liapunov function** (3 Punkte)

Show that the system  $\dot{x} = y - x^3$ ,  $\dot{y} = -x - y^3$  has no closed orbits by constructing a Liapunov function  $V = ax^2 + by^2$  with suitable  $a, b$ .

(3) **Absence of closed orbits** (2 Punkte)

Consider  $\dot{x} = x^2 - y - 1$ ,  $\dot{y} = y(x - 2)$ .

- Show that there are three fixed points and classify them.
- By considering the three straight lines through pairs of fixed points, show that there are no closed orbits.
- Plot the phase portrait.

(4) **Index theory** (3 Punkte)

Read and understand Section 6.8 in Strogatz until Theorem 6.8.2.

- Show that each of the following fixed points has an index equal to +1:  
(i) stable spiral (ii) unstable spiral (iii) center (iv) star (v) degenerate node.
- Use index theory to show that the system  $\dot{x} = x(4 - y - x^2)$ ,  $\dot{y} = y(x - 1)$  has no closed orbits.